



Experimental Studies in Matching Markets

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 - information subjects' have regarding others' preferences is unclear.
- A complement to other kinds of investigation.



School Choice

- School choice programs
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 - give families an opportunity to express their preferences.



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 - deal with the assignment of children to public schools, and
 - give families an opportunity to express their preferences.
- Model of many-to-one, two-sided matching markets where only *one* side is strategic.
- Seminal paper by Abdulkadiroğlu and Sönmez (2003) in AER
 - describes the problems in many US school districts
 - “Boston” mechanism (BOS) is problematic: manipulable, inefficient, unfair.
 - proposes specific school choice mechanisms as a solution
 - Gale-Shapley (GS) mechanism: strategy-proof, fair
 - Top Trading Cycles (TTC): strategy-proof, Pareto efficient.



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- Chen and Sönmez (2006), in *JET*
- Featherstone and Niederle (2008, 2011), *working papers*
- Pais and Pintér (2008), in *GEB*
- Calsamiglia, Haeringer, and Klijn (2010), in *AER*
- Braun, Dwenger, Kübler, and Westkamp (2011), *working paper*
- Klijn, Pais, and Vorsatz (2012), in *Exp. Ecs*
- Chen and Kesten (2013), *working papers*.



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 - The extent of preference manipulation in BOS
 - The extent to which subjects recognize truth-telling as dominant in GS and TTC
 - The impact on efficiency comparisons across mechanisms.



The Experiment

- One-shot game of incomplete information



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- 3×2 design:
 - 3 mechanisms: BOS, SOSM, TTC
 - 2 sets of payoffs: one designed, one random.



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- 36 students, 7 schools



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- 2 sessions per treatment
- 36 students, 7 schools
- Schools A and B have capacity 3; schools C to G have capacity 6.



Preferences and Priorities

- In the designed environment, students' preferences depend on
 - Proximity: students 1 to 3 are in A's district; students 4 to 6 are in B's district; 7 to 12 are in C's district, etc.



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- Priorities are such that
 - Students living in the district of a school have priority over all students from other districts
 - Within priority classes, students are ordered according to a random draw.



Notation

- $x > y$ denotes that a measure under mechanism x is greater than the corresponding measure under mechanism y at the 5% significance level or less
- $x \geq y$ denotes that a measure under mechanism x is greater than the corresponding measure under mechanism y at the 10% level of significance or less (but not supported at 5% level)
- $x \sim y$ denotes that a measure under mechanism x is not significantly different from the corresponding measure under mechanism y at the 10% significance level



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- District school bias (DSB):
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 - Under BOS, roughly two thirds of the subjects use DSB.



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- Using recombinant estimation, efficiency levels (expected per capita payoffs levels) are such that
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- Contrary to theory, GS is more efficient than TTC.



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- Contrary to theory, GS is more efficient than TTC.
- Simulations were used to confirm the efficiency comparison.



Recombinant Estimation (Mullin and Reiley, 2006)

- Each treatment is a one-shot game and was run twice.
- We can recombine students' strategies to compute mean payoffs if players' groupings were different (2^{36} different recombinations).
- Chen and Sönmez (2006) —henceforth CS06— generates 200 recombinations per subject for each of the 72 subjects.
- But, with a higher number of recombinations, Calsamiglia, Haeringer, and Klijn (2011) find that GS is not superior to TTC in the designed environment ($GS \geq TTC$).



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 - there's a very high preference manipulation rate
 - efficiency is significantly lower.
- This gives additional weight to Abdulkadiroğlu and Sönmez recommendation to replace BOS by either of the two mechanisms.



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Calsamiglia, Haeringer, and Klijn (2010) was motivated by Haeringer and Klijn (2009) in *JET* showing that when lists are constrained:



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- Stringent conditions on priorities are necessary and sufficient for stable Nash equilibrium outcomes under GS and TTC.



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Reconduct the CS06 experiment with a constraint on the length of submitted preferences.



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- $3 \times 2 \times 2$ design:
 - 3 mechanisms: BOS, GS, TTC
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- Truncated truth-telling (choices are 3 most preferred)
 - Less truncated truth-telling under constrained choice
 - In the constrained setting, $GS \sim TTC \sim BOS$ (in contrast with CS06).
- Manipulation:
 - Safety school bias (SSB), ie, including the district school when ranked 4th or below: appears in the 3 mechanisms (more important under GS and TTC).



Results: Efficiency

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 - In the constrained, designed environment, $TTC > GS > BOS$
 - In the constrained, uncorrelated environment, $TTC \sim GS \sim BOS$, but $TTC > BOS$
 - In both the designed and uncorrelated environment, BOS and GS are significantly less efficient in the constrained case, whereas for TTC the difference is not significant.



Conclusion

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- Many exhibit a safety school effect



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- Subjects do not truncate and behave “rationally”
- Many exhibit a safety school effect
- The performance of both GS and TTC is not substantially better than the BOS.



Information

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- Pais and Pintér (2008) attempts to determine how the level of information agents hold affects behavior and the performance of different mechanisms.



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- 3×4 design:
 - 3 mechanisms: BOS, GS, TTC



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 - 4 information scenarios: Zero, Low, Partial (on priorities), Complete



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- One-shot game
- 3×4 design:
 - 3 mechanisms: BOS, GS, TTC
 - 4 information scenarios: Zero, Low, Partial (on priorities), Complete
- 5 students, 3 schools (2 schools have capacity 2, the third school has capacity 1).



Results: Strategies

- Truth-telling
 - Truth-telling rates are significantly higher under Zero information



Results: Strategies

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 - Under all information levels, $TTC > BOS$



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 - Under Partial and Full information, $GS > BOS$
 - Under Zero and Full information, $TTC > GS$.



Results: Efficiency

- Efficiency levels (average efficiency of all the groups) are such that
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- Efficiency levels (average efficiency of all the groups) are such that
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 - Under Zero information, $TTC \sim GS \sim BOS$
 - Under Partial and Full information, $TTC > GS$ and $TTC \geq BOS$
 - Zero information results in significantly higher efficiency levels under GS and BOS



Results: Efficiency

- Efficiency levels (average efficiency of all the groups) are such that
 - Under Zero information, $TTC \sim GS \sim BOS$
 - Under Partial and Full information, $TTC > GS$ and $TTC \geq BOS$
 - Zero information results in significantly higher efficiency levels under GS and BOS
 - Information does not affect efficiency under TTC.



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 - Similar truth-telling rates in some informational settings



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Conclusion

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 - Similar truth-telling rates in some informational settings
 - But higher efficiency levels.
- Information is important
 - Truth-telling rates are much higher when information is low
 - Efficiency is higher with low information under all mechanisms but TTC, which appears to be less sensitive to information.



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 - does this happen in all environments?
 - could agents be best-replying?
- Featherstone and Niederle (2011) compares GS and BOS in two environments:
 - When truth-telling is an equilibrium under BOS
 - When there is a unique non-truth-telling equilibrium under BOS.



The Experiment

- Repeated game of incomplete information (subjects know own preferences and the distribution from which preferences are drawn)



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 - truth-telling is a Bayes–Nash equilibrium under GS and BOS.
- Aligned preferences:
 - all students have the same preferences, two classes of students: top and average, top have priority over average
 - truth-telling is a Bayes–Nash equilibrium under GS, while BOS has a unique non–truth–telling equilibrium.



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 - all students have the same preferences, two classes of students: top and average, top have priority over average
 - truth-telling is a Bayes–Nash equilibrium under GS, while BOS has a unique non-truth-telling equilibrium.
- Within-subjects design: subjects played for 15 periods with aligned and for 15 periods with uncorrelated preferences and they see the match after every period.



Results: Strategies

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Results: Strategies

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 - With uncorrelated preferences, $GS \sim BOS$
 - With aligned preferences, $GS > BOS$ (and subjects manipulate in a sub-optimal way under BOS).



Results: Efficiency

- Fraction of students receiving their first choices:
 - With uncorrelated preferences: $BOS > GS$ (in fact, BOS stochastically dominates GS)



Results: Efficiency

- Fraction of students receiving their first choices:
 - With uncorrelated preferences: $BOS > GS$ (in fact, BOS stochastically dominates GS)
 - With aligned preferences: top students are better off under GS, average students are better off under BOS.



Conclusion

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- Truth-telling equilibria that are not implemented in dominant strategies have the potential to succeed
- In some environments, BOS may dominate GS.



Preference Intensities

- Klijn, Pais, and Vorsatz (2012) motivated by Abdulkadiroğlu, Che, and Yasuda (2011), in AER, where BOS may dominate GS from an *ex ante* point of view.



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- Klijn, Pais, and Vorsatz (2012) motivated by Abdulkadiroğlu, Che, and Yasuda (2011), in AER, where BOS may dominate GS from an *ex ante* point of view.
- BOS is manipulable and may be sensible to preference intensities and attitudes toward risk.



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- Two phases:
 - First phase: eliciting subjects' degree of risk aversion using the paired lottery choice design of Holt and Laury (2002)



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- 3 students, 3 one-seat schools



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 - Second phase: school choice game under complete information with a 2×2 design:
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Each subject plays the school choice game 3 times, with different payoff structures.



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Strategies:

- Cardinal preferences affect behavior



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- In the constrained setting, $BOS > GS$.



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- In the unconstrained setting, $GS > BOS$
- In the constrained setting, $BOS > GS$.

Stability (proportion of stable outcomes) is such that:

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Results

Strategies:

- Cardinal preferences affect behavior
- GS is more robust to changes in cardinal preferences than BOS
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- GS is more “stability–robust”.



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Conclusion

- Behavior is affected by cardinal preferences and risk aversion. In particular,
 1. under GS, highly risk averse agents tend to play safer strategies
 2. GS is more robust to changes in payoffs (more predictable), while BOS induces agents to reveal their cardinal preferences more often.
- BOS does not necessarily perform worse than GS in terms of efficiency, while GS is more stable and “stability–robust”.



Parallel Mechanisms

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- CCA lies between BOS, where every step is final, and DA, where every step is temporary until all seats are filled.



CCA with 2 Parallel Choices

Round $t = 0$

- Each student applies to the school she ranked first. A school tentatively retains the students with the highest priority up to its quota and rejects the remaining students.



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- The round terminates when each student either has her application retained by some school or was rejected by her 2 first choices. At this point all tentative assignments are final and the quota of each school is reduced by the number of students assigned to it.



SH with 2 Parallel Choices

In general,

Round $t \geq 1$

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- 4-school environment: BOS and CCA have a unique Nash equilibrium (stable, Pareto inefficient) outcome; GS has an additional (unstable, Pareto efficient) equilibrium outcome
- 6-school environment: correlated preferences; larger set of Nash equilibrium outcomes; more equilibria under CCA than BOS.



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- Learning separates the performance of the mechanisms in terms of efficiency.



Other Matching Problems

- Two-sided matching

Echenique, Wilson, and Yariv (2009), *working paper*

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- House allocation problems

Chen and Sönmez (2002), in *AER*

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 - market features (cardinal representation of preferences and size of the core) affect the stability of the outcome and speed of convergence.



Pais, Pintér, and Veszteg, 2011

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 - with substantial information $TTC > BOS > GS$.



Decentralized Matching

- Nalbantian and Schotter (1995) analyzes decentralized matching under incomplete information and includes private negotiations between potential match partners.
- Kagel and Roth (2000) analyzes the transition from decentralized to centralized clearinghouses, when the market features lead to inefficient matching through unraveling.
- Haruvy and Ünver (2007) analyzes a decentralized market where one side of the market can make offers and markets are repeated. It shows that the optimal stable matching for the proposing–side of the market is usually reached, independently of the information subjects hold.
- Niederle and Roth (2009) analyzes an incomplete information setting where firms make offers to workers over several experimental periods and study the effect of offer structure (exploding or open offers) on the information that gets used in the final matching and consequent market efficiency. Later, thick markets may appear by allowing only open offers.



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 - convergence to stability is the quickest when there is commitment.
 - Efficiency:
 - commitment corresponds to the highest efficiency levels, whereas costly offers correspond to the lowest.



House Allocation Problems

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